

EKSISTENSI INTERPOLAN SINUSOIDA BERDIMENSI DUA

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A B S T R A K

Dalam makalah ini akan dibahas tentang bukti dari syarat cukup bagi eksistensi interpolan sinusoida berdimensi dua yaitu berupa fungsi berbentuk *deret sinus Fourier ganda* yang diketahui melalui beberapa buah titik (x_i, y_j, c_{ij}) , dengan $0 < x_i < 1$, dan $0 < y_j < 1$. Pembuktian akan dilakukan melalui dekomposisi matriks yang memuat dua buah variabel menjadi perkalian dari pada dua buah matriks yang masing-masing memuat satu variabel, serta menunjukkan bahwa kedua matriks tersebut adalah nonsingulir.

Kata Kunci: Interpolan, sinusoida, dekomposisi.

1. PENDAHULUAN

Dalam rangka menjamin keberadaan (eksistensi) suatu fungsi dalam masalah interpolasi, maka untuk menunjukan adanya interpolan berbentuk sinusoida berdimensi dua, yaitu deret sinus *Fourier ganda*:

$$u(x,y) = \sum_{m=1}^M \sum_{n=1}^N [a_{mn} \sin m\pi x \cdot \sin n\pi y]$$
 yang melalui K buah titik: (x_i, y_j, c_{ij}) , dengan $0 < x_i < 1$, dan $0 < y_j < 1$, penulis akan membaginya dalam dua tahap. Tahap-1 terlebih dahulu akan membahas tentang eksistensi fungsi $u(x,y)$ yang melalui sejumlah $K = (M.N)$ buah titik homogen: (x_i, y_j, c_{ij}) dengan $0 < x_1 < \dots < x_M < 1$ dan $0 < y_1 < \dots < y_N < 1$. Selanjutnya dalam tahap-2 akan dibahas tentang eksistensi fungsi $u(x,y)$ yang melalui K buah titik sembarang: (x_i, y_i, c_i) dengan $0 < x_i < 1$, dan $0 < y_i < 1$ untuk $i = 1, 2, \dots, K$.

Dalam masalah satu dimensi, yaitu bagaimana menjamin eksistensi fungsi berbentuk deret sinus Fourier $u(x,y) = \sum_{m=1}^N [a_m \sin m\pi x]$ yang melalui N buah titik: (x_i, c_i) dengan $0 < x_i < 1$, telah dibuktikan dalam [3] dan digunakan dalam [5] bahwa berlaku:

$$\begin{vmatrix} \sin \pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin N\pi x_1 \\ \sin \pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin N\pi x_2 \\ \sin \pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin N\pi x_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi x_N & \sin 2\pi x_N & \sin 3\pi x_N & \dots & \sin N\pi x_N \end{vmatrix} \neq 0$$

2. Eksistensi fungsi $u(x,y)$ yang Melalui $(M.N)$ Buah Titik

Untuk mengetahui eksistensi fungsi $u(x,y) := \sum_{m=1}^M \sum_{n=1}^N [a_{mn} \sin m\pi x \cdot \sin n\pi y]$ yang melalui $(M.N)$ buah titik: (x_i, y_j, c_{ij}) , di mana $0 < x_1 < \dots < x_M < 1$ dan $0 < y_1 < \dots < y_N < 1$, terlebih dahulu kita substitusikan nilai (x_i, y_j, c_{ij}) tersebut pada fungsi $u(x,y)$ di atas sehingga membentuk *sistem persamaan linear* dengan $(M.N)$ buah persamaan dan $(M.N)$ buah variabel: [1, 4]

$$u(x_i, y_j) = \sum_{m=1}^M \sum_{n=1}^N [a_{mn} \sin m\pi x_i \cdot \sin n\pi y_j] = c_{ij}$$

Dalam bentuk persamaan matriks, dapat ditulis:

$$\begin{bmatrix} \sin\pi x_1 \cdot \sin\pi y_1 & \dots & \sin M\pi x_1 \cdot \sin\pi y_1 & \sin\pi x_1 \cdot \sin 2\pi y_1 & \dots & \sin M\pi x_1 \cdot \sin 2\pi y_1 & \dots & \dots & \sin\pi x_1 \cdot \sin N\pi y_1 & \dots & \sin M\pi x_1 \cdot \sin N\pi y_1 \\ \vdots & & & & & & & & & & \vdots \\ \sin\pi x_M \cdot \sin\pi y_1 & \dots & \sin M\pi x_M \cdot \sin\pi y_1 & \sin\pi x_M \cdot \sin 2\pi y_1 & \dots & \sin M\pi x_M \cdot \sin 2\pi y_1 & \dots & \dots & \sin\pi x_M \cdot \sin N\pi y_1 & \dots & \sin M\pi x_M \cdot \sin N\pi y_1 \\ \sin\pi x_1 \cdot \sin\pi y_2 & \dots & \sin M\pi x_1 \cdot \sin\pi y_2 & \sin\pi x_1 \cdot \sin 2\pi y_2 & \dots & \sin M\pi x_1 \cdot \sin 2\pi y_2 & \dots & \dots & \sin\pi x_1 \cdot \sin N\pi y_2 & \dots & \sin M\pi x_1 \cdot \sin N\pi y_2 \\ \vdots & & & & & & & & & & \vdots \\ \sin\pi x_M \cdot \sin\pi y_2 & \dots & \sin M\pi x_M \cdot \sin\pi y_2 & \sin\pi x_M \cdot \sin 2\pi y_2 & \dots & \sin M\pi x_M \cdot \sin 2\pi y_2 & \dots & \dots & & & \\ \vdots & & & & & & & & & & \vdots \\ \vdots & & & & & & & & & & \vdots \\ \sin\pi x_1 \cdot \sin\pi y_N & \dots & \sin M\pi x_1 \cdot \sin\pi y_N & \sin\pi x_1 \cdot \sin 2\pi y_N & \dots & \sin M\pi x_1 \cdot \sin 2\pi y_N & \dots & \dots & & & \\ \vdots & & & & & & & & & & \vdots \\ \sin\pi x_M \cdot \sin\pi y_N & \dots & \sin M\pi x_M \cdot \sin\pi y_N & \sin\pi x_M \cdot \sin 2\pi y_N & \dots & \sin M\pi x_M \cdot \sin 2\pi y_N & \dots & \dots & \dots & & \sin M\pi x_M \cdot \sin N\pi y_N \end{bmatrix} \cdot \begin{bmatrix} a_{11} \\ \dots \\ a_{M1} \\ a_{12} \\ \dots \\ a_{M2} \\ \dots \\ \dots \\ a_{1N} \\ \dots \\ a_{MN} \end{bmatrix} = \begin{bmatrix} c_{11} \\ \dots \\ c_{M1} \\ c_{12} \\ \dots \\ c_{M2} \\ \dots \\ \dots \\ c_{1N} \\ \dots \\ c_{MN} \end{bmatrix}$$

yang secara sederhana dapat dinyatakan sebagai: $\mathbf{A} \cdot (a_{mn}) = (c_{mn})$, di mana \mathbf{A} adalah matriks berorde $(M.N) \times (M.N)$.

Dengan demikian agar supaya fungsi $u(x,y)$ yang melalui titik-titik tadi terdefinisi (ada), maka persamaan linear di atas harus mempunyai solusi, artinya bahwa determinan dari matriks \mathbf{A} tidak boleh sama dengan nol. Artinya bahwa syarat cukup bagi eksistensi fungsi $u(x,y)$ adalah $\text{Det } \mathbf{A} \neq 0$.

Untuk menunjukkan hal tersebut, terlebih dahulu matriks \mathbf{A} di "dekomposisi" menjadi:

$$\mathbf{A}_{(M.N) \times (M.N)} = \mathbf{A}^x_{(M.N) \times (M.N)} \cdot \mathbf{A}^y_{(M.N) \times (M.N)} \quad \dots(1)$$

dimana $\mathbf{A}^x_{(M.N) \times (M.N)} =$

$$\begin{bmatrix} \sin\pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin M\pi x_1 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ \sin\pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin M\pi x_2 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ \sin\pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin M\pi x_3 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin\pi x_M & \sin 2\pi x_M & \sin 3\pi x_M & \dots & \sin M\pi x_M & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ \hline 0 & 0 & 0 & \dots & 0 & \sin\pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin M\pi x_1 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 & \sin\pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin M\pi x_2 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 & \sin\pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin M\pi x_3 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 & \sin\pi x_M & \sin 2\pi x_M & \sin 3\pi x_M & \dots & \sin M\pi x_M & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 \\ \hline 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \sin\pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin M\pi x_1 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \sin\pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin M\pi x_2 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \sin\pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin M\pi x_3 & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \sin\pi x_M & \sin 2\pi x_M & \sin 3\pi x_M & \dots & \sin M\pi x_M & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & \sin\pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin M\pi x_1 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & \sin\pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin M\pi x_2 & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & \sin\pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin M\pi x_3 & \dots & \dots & \dots & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & \dots & \sin\pi x_M & \sin 2\pi x_M & \sin 3\pi x_M & \dots & \sin M\pi x_M & \dots & \dots & \dots & \dots & \dots \end{bmatrix}$$

dan \mathbf{A}^y $(M.N) \times (M.N) =$

$$\begin{bmatrix}
 \sin\pi y_1 & 0 & 0 & \dots & 0 & \sin 2\pi y_1 & 0 & 0 & \dots & 0 & \sin 3\pi y_1 & 0 & 0 & \dots & 0 & \dots & \sin N\pi y_1 & 0 & 0 & \dots & 0 \\
 0 & \sin\pi y_1 & 0 & \dots & 0 & 0 & \sin 2\pi y_1 & 0 & \dots & 0 & 0 & \sin 3\pi y_1 & 0 & \dots & 0 & \dots & 0 & \sin N\pi y_1 & 0 & \dots & 0 \\
 0 & 0 & \sin\pi y_1 & \dots & 0 & 0 & 0 & \sin 2\pi y_1 & \dots & 0 & 0 & 0 & \sin 3\pi y_1 & \dots & 0 & \dots & 0 & 0 & \sin N\pi y_1 & \dots & 0 \\
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
 0 & 0 & 0 & \dots & \sin\pi y_1 & 0 & 0 & 0 & \dots & \sin 2\pi y_1 & 0 & 0 & 0 & \dots & \sin 3\pi y_1 & \dots & 0 & 0 & 0 & \dots & \sin N\pi y_1 \\
 \hline
 \sin\pi y_2 & 0 & 0 & \dots & 0 & \sin 2\pi y_2 & 0 & 0 & \dots & 0 & \sin 3\pi y_2 & 0 & 0 & \dots & 0 & \dots & \sin N\pi y_2 & 0 & 0 & \dots & 0 \\
 0 & \sin\pi y_2 & 0 & \dots & 0 & 0 & \sin 2\pi y_2 & 0 & \dots & 0 & 0 & \sin 3\pi y_2 & 0 & \dots & 0 & \dots & 0 & \sin N\pi y_2 & 0 & \dots & 0 \\
 0 & 0 & \sin\pi y_2 & \dots & 0 & 0 & 0 & \sin 2\pi y_2 & \dots & 0 & 0 & 0 & \sin 3\pi y_2 & \dots & 0 & \dots & 0 & 0 & \sin N\pi y_2 & \dots & 0 \\
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
 0 & 0 & 0 & \dots & \sin\pi y_2 & 0 & 0 & 0 & \dots & \sin 2\pi y_2 & 0 & 0 & 0 & \dots & \sin 3\pi y_2 & \dots & 0 & 0 & 0 & \dots & \sin N\pi y_2 \\
 \hline
 \sin\pi y_3 & 0 & 0 & \dots & 0 & \sin 2\pi y_3 & 0 & 0 & \dots & 0 & \sin 3\pi y_3 & 0 & 0 & \dots & 0 & \dots & \sin N\pi y_3 & 0 & 0 & \dots & 0 \\
 0 & \sin\pi y_3 & 0 & \dots & 0 & 0 & \sin 2\pi y_3 & 0 & \dots & 0 & 0 & \sin 3\pi y_3 & 0 & \dots & 0 & \dots & 0 & \sin N\pi y_3 & 0 & \dots & 0 \\
 0 & 0 & \sin\pi y_3 & \dots & 0 & 0 & 0 & \sin 2\pi y_3 & \dots & 0 & 0 & 0 & \sin 3\pi y_3 & \dots & 0 & \dots & 0 & 0 & \sin N\pi y_3 & \dots & 0 \\
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
 0 & 0 & 0 & \dots & \sin\pi y_3 & 0 & 0 & 0 & \dots & \sin 2\pi y_3 & 0 & 0 & 0 & \dots & \sin 3\pi y_3 & \dots & 0 & 0 & 0 & \dots & \sin N\pi y_3 \\
 \hline
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
 \hline
 \sin\pi y_N & 0 & 0 & \dots & 0 & \sin 2\pi y_N & 0 & 0 & \dots & 0 & \sin 3\pi y_N & 0 & 0 & \dots & 0 & \dots & \sin N\pi y_N & 0 & 0 & \dots & 0 \\
 0 & \sin\pi y_N & 0 & \dots & 0 & 0 & \sin 2\pi y_N & 0 & \dots & 0 & 0 & \sin 3\pi y_N & 0 & \dots & 0 & \dots & 0 & \sin N\pi y_N & 0 & \dots & 0 \\
 0 & 0 & \sin\pi y_N & \dots & 0 & 0 & 0 & \sin 2\pi y_N & \dots & 0 & 0 & 0 & \sin 3\pi y_N & \dots & 0 & \dots & 0 & 0 & \sin N\pi y_N & \dots & 0 \\
 \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
 0 & 0 & 0 & \dots & \sin\pi y_N & 0 & 0 & 0 & \dots & \sin 2\pi y_N & 0 & 0 & 0 & \dots & \sin 3\pi y_N & \dots & 0 & 0 & 0 & \dots & \sin N\pi y_N
 \end{bmatrix}$$

Untuk membuktikan bahwa kedua determinan matriks tidak nol, terlebih dahulu akan disajikan dua proposisi berikut.

Proposisi-1:

$$\text{Det } \mathbf{A}^x \text{ } (M.N) \times (M.N) = \begin{vmatrix} \sin \pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin M\pi x_1 \\ \sin \pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin M\pi x_2 \\ \sin \pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin M\pi x_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi x_M & \sin 2\pi x_M & \sin 3\pi x_M & \dots & \sin M\pi x_M \end{vmatrix}^N \quad \dots(2)$$

Bukti:

\mathbf{A}^x adalah matriks berorde $(M.N) \times (M.N)$ yang terdiri dari N buah matriks partisi yang masing-masing berorde $(M.N)$ dan membentuk matriks diagonal pada \mathbf{A}^x .

Melalui operasi baris elementer [6], iterasi pertamanya adalah:

$$\text{Baris : } B_{[i.M+2]} - \frac{\sin\pi x_2}{\sin\pi x_1} \cdot B_{i.M+1} ; B_{[i.M+3]} - \frac{\sin\pi x_3}{\sin\pi x_1} \cdot B_{i.M+1} ; \dots ; B_{[i.M+M]} - \frac{\sin\pi x_M}{\sin\pi x_1} \cdot B_{i.M+1}.$$

dengan $i = 0, 1, \dots, (N-1).M$

Selanjutnya dengan pola yang sama, iterasi diteruskan sampai iterasi ke-(N-1). Hasilnya, matriks \mathbf{A}^x akan berubah menjadi matriks segi tiga atas dengan nilai determinan sama dengan perkalian unsur-unsur diagonalnya. Karena matriks partisinya sama, sebanyak N buah, maka nilai determinan tersebut sama dengan perkalian dari determinan matriks parisi masing-masing sebanyak N. Jadi (2) terbukti. ■

Proposisi-2:

$$\text{Det } \mathbf{A}^y_{(M \times N) \times (M \times N)} = \begin{vmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \dots & \sin N\pi y_1 \\ \sin \pi y_2 & \sin 2\pi y_2 & \sin 3\pi y_2 & \dots & \sin N\pi y_2 \\ \sin \pi y_3 & \sin 2\pi y_3 & \sin 3\pi y_3 & \dots & \sin N\pi y_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi y_N & \sin 2\pi y_N & \sin 3\pi y_N & \dots & \sin N\pi y_N \end{vmatrix}^M \quad \dots(3)$$

Bukti:

Langkah pertama akan dihitung nilai dari

$$\begin{vmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \dots & \sin N\pi y_1 \\ \sin \pi y_2 & \sin 2\pi y_2 & \sin 3\pi y_2 & \dots & \sin N\pi y_2 \\ \sin \pi y_3 & \sin 2\pi y_3 & \sin 3\pi y_3 & \dots & \sin N\pi y_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi y_N & \sin 2\pi y_N & \sin 3\pi y_N & \dots & \sin N\pi y_N \end{vmatrix}.$$

Melalui operasi baris elementer pada iterasi-1 dengan baris $B_2 - \frac{\sin \pi y_2}{\sin \pi y_1} \cdot B_1$;

$B_3 - \frac{\sin \pi y_3}{\sin \pi y_1} \cdot B_1$; ... ; $B_i - \frac{\sin \pi y_i}{\sin \pi y_1} \cdot B_1$, $i = 2, 3, \dots, N$, hasilnya adalah

$$= \text{Det} \begin{pmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \sin 4\pi y_1 & \dots & \sin N\pi y_1 \\ 0 & A_{22}^{(1)} & A_{23}^{(1)} & A_{24}^{(1)} & \dots & A_{2N}^{(1)} \\ 0 & A_{32}^{(1)} & A_{33}^{(1)} & A_{34}^{(1)} & \dots & A_{3N}^{(1)} \\ 0 & A_{42}^{(1)} & A_{43}^{(1)} & A_{44}^{(1)} & \dots & A_{4N}^{(1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & A_{N2}^{(1)} & A_{N3}^{(1)} & A_{N4}^{(1)} & \dots & A_{NN}^{(1)} \end{pmatrix}$$

di mana: $A_{22}^{(1)} = \sin 2\pi y_2 - \frac{\sin \pi y_2}{\sin \pi y_1} \cdot \sin 2\pi y_1$; $A_{32}^{(1)} = \sin 2\pi y_3 - \frac{\sin \pi y_3}{\sin \pi y_1} \cdot \sin 2\pi y_1$; dst ... ,

yang secara umum: $A_{ij}^{(1)} = \sin j\pi y_i - \frac{\sin \pi y_i}{\sin \pi y_1} \cdot \sin j\pi y_1$

Selanjutnya setelah dilakukan iterasi-2 di mana

baris $B_3 - \frac{A_{32}^{(1)}}{A_{22}^{(1)}} \cdot B_2$; $B_4 - \frac{A_{42}^{(1)}}{A_{22}^{(1)}} \cdot B_2$; ... ; $B_i - \frac{A_{i2}^{(1)}}{A_{22}^{(1)}} \cdot B_2$, $i = 3, 4, \dots, N$ dan

iterasi-3 di mana

baris $B_4 - \frac{A_{43}^{(2)}}{A_{33}^{(2)}} \cdot B_3$; ... ; $B_i - \frac{A_{i3}^{(2)}}{A_{33}^{(2)}} \cdot B_3$, $i = 4, \dots, N$, maka hasilnya menjadi

$$= \text{Det} \begin{pmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \sin 4\pi y_1 & \dots & \sin N\pi y_1 \\ 0 & A_{22}^{(1)} & A_{23}^{(1)} & A_{24}^{(1)} & \dots & A_{2N}^{(1)} \\ 0 & 0 & A_{33}^{(2)} & A_{34}^{(2)} & \dots & A_{3N}^{(2)} \\ 0 & 0 & 0 & A_{44}^{(3)} & \dots & A_{4N}^{(3)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & A_{N4}^{(3)} & \dots & A_{NN}^{(3)} \end{pmatrix}$$

dengan $A_{ij}^{(2)} = A_{ij}^{(1)} - \frac{A_{i2}^{(1)}}{A_{22}^{(1)}} \cdot A_{2j}^{(1)}$ dan $A_{ij}^{(3)} = A_{ij}^{(2)} - \frac{A_{i3}^{(2)}}{A_{33}^{(2)}} \cdot A_{3j}^{(2)}$

Apabila proses iterasi diteruskan, maka setelah iterasi ke-(N-1), diperoleh:

$$= \text{Det} \begin{pmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \sin 4\pi y_1 & \dots & \sin N\pi y_1 \\ 0 & A_{22}^{(1)} & A_{23}^{(1)} & A_{24}^{(1)} & \dots & A_{2N}^{(1)} \\ 0 & 0 & A_{33}^{(2)} & A_{34}^{(2)} & \dots & A_{3N}^{(2)} \\ 0 & 0 & 0 & A_{44}^{(3)} & \dots & A_{4N}^{(3)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & A_{NN}^{(N-1)} \end{pmatrix}$$

$$= \sin \pi y_1 \cdot A_{22}^{(1)} \cdot A_{33}^{(2)} \cdot A_{44}^{(3)} \dots A_{NN}^{(N-1)}$$

$$= \prod_{i=1}^N \left(A_{ii}^{(i-1)} \right) \quad \dots(4)$$

di mana : $A_{11}^{(0)} = \sin \pi y_1$, $A_{22}^{(1)} = \sin 2\pi y_2 - \frac{\sin \pi y_2}{\sin \pi y_1} \cdot \sin 2\pi y_1$, ...

secara umum: $A_{ij}^{(k)} = A_{ij}^{(k-1)} - \frac{A_{ik}^{(k-1)}}{A_{kk}^{(k-1)}} \cdot A_{kj}^{(k-1)}$.

Langkah selanjutnya adalah membuktikan bahwa

$$\text{Det } \mathbf{A}^y_{(M \times N) \times (M \times N)} = \prod_{i=1}^N \left(A_{ii}^{(i-1)} \right).$$

Melalui operasi baris elementer, setelah iterasi-1 dengan:

baris $B_{[(i-1)M+1]} - \frac{\sin \pi y_i}{\sin \pi y_1} \cdot B_1$, $B_{[(i-1)M+2]} - \frac{\sin \pi y_i}{\sin \pi y_1} \cdot B_2$ dst...,

yang secara umum: $B_{[(i-1)M+j]} - \frac{\sin \pi y_i}{\sin \pi y_1} \cdot B_j$, $i = 2, 3, \dots, N-1$; $j = 1, 2, \dots, M$, maka hasilnya

det \mathbf{A}^y sama dengan determinan matriks:

$\sin \pi y_1$	0	0	...	0	$\sin 2\pi y_1$	0	0	...	0	$\sin 3\pi y_1$	0	0	...	0	...	$\sin N\pi y_1$	0	0	...	0
0	$\sin \pi y_1$	0	...	0	0	$\sin 2\pi y_1$	0	...	0	0	$\sin 3\pi y_1$	0	...	0	...	0	$\sin N\pi y_1$	0	...	0
0	0	$\sin \pi y_1$...	0	0	0	$\sin 2\pi y_1$...	0	0	0	$\sin 3\pi y_1$...	0	...	0	0	$\sin N\pi y_1$...	0
...
0	0	0	...	$\sin \pi y_1$	0	0	0	...	$\sin 2\pi y_1$	0	0	0	...	$\sin 3\pi y_1$...	0	0	0	...	$\sin N\pi y_1$
0	0	0	...	0	$A_{22}^{(0)}$	0	0	...	0	$A_{23}^{(0)}$	0	0	...	0	...	$A_{2N}^{(0)}$	0	0	...	0
0	0	0	...	0	0	$A_{22}^{(1)}$	0	...	0	0	$A_{23}^{(1)}$	0	...	0	...	0	$A_{2N}^{(1)}$	0	...	0
0	0	0	...	0	0	0	$A_{22}^{(2)}$...	0	0	0	$A_{23}^{(2)}$...	0	...	0	0	$A_{2N}^{(2)}$...	0
...
0	0	0	...	0	0	0	0	...	$A_{22}^{(2)}$	0	0	0	...	$A_{23}^{(2)}$...	0	0	0	...	$A_{2N}^{(2)}$
0	0	0	...	0	$A_{32}^{(0)}$	0	0	...	0	$A_{33}^{(0)}$	0	0	...	0	...	$A_{3N}^{(0)}$	0	0	...	0
0	0	0	...	0	0	$A_{32}^{(1)}$	0	...	0	0	$A_{33}^{(1)}$	0	...	0	...	0	$A_{3N}^{(1)}$	0	...	0
0	0	0	...	0	0	0	$A_{32}^{(2)}$...	0	0	0	$A_{33}^{(2)}$...	0	...	0	0	$A_{3N}^{(2)}$...	0
...
0	0	0	...	0	0	0	0	...	$A_{32}^{(2)}$	0	0	0	...	$A_{33}^{(2)}$...	0	0	0	...	$A_{3N}^{(2)}$
...
0	0	0	...	0	$A_{N2}^{(0)}$	0	0	...	0	$A_{N3}^{(0)}$	0	0	...	0	...	$A_{NN}^{(0)}$	0	0	...	0
0	0	0	...	0	0	$A_{N2}^{(1)}$	0	...	0	0	$A_{N3}^{(1)}$	0	...	0	...	0	$A_{NN}^{(1)}$	0	...	0
0	0	0	...	0	0	0	$A_{N2}^{(2)}$...	0	0	0	$A_{N3}^{(2)}$...	0	...	0	0	$A_{NN}^{(2)}$...	0
...
0	0	0	...	0	0	0	0	...	$A_{N2}^{(2)}$	0	0	0	...	$A_{N3}^{(2)}$...	0	0	0	...	$A_{NN}^{(2)}$
...

di mana: $A_{22}^{(1)} = \sin 2\pi y_2 - \frac{\sin \pi y_2}{\sin \pi y_1} \cdot \sin 2\pi y_1$; $A_{32}^{(1)} = \sin 2\pi y_3 - \frac{\sin \pi y_3}{\sin \pi y_1} \cdot \sin 2\pi y_1$; dst ... ,

yang secara umum: $A_{ij}^{(1)} = \sin j\pi y_i - \frac{\sin \pi y_i}{\sin \pi y_1} \cdot \sin j\pi y_1$

Setelah iterasi-2 dengan baris $B_{[2M+1]} - \frac{A_{32}^{(1)}}{A_{22}^{(1)}} \cdot B_{M+1}$, $B_{[2M+2]} - \frac{A_{33}^{(1)}}{A_{22}^{(1)}} \cdot B_{M+2}$ dst...

yang secara umum: $B_{[(i-1)M+j]} - \frac{A_{i2}^{(1)}}{A_{22}^{(1)}} \cdot B_{M+j}$; $i = 3, 4, \dots, N-1$; $j = 1, 2, \dots, M$, hasilnya

adalah sama dengan determinan matriks:

$\sin \pi y_1$	0	0	...	0	$\sin 2\pi y_1$	0	0	...	0	$\sin 3\pi y_1$	0	0	...	0	$\sin 4\pi y_1$	0	0	...	0	...
0	$\sin \pi y_1$	0	...	0	0	$\sin 2\pi y_1$	0	...	0	0	$\sin 3\pi y_1$	0	...	0	0	$\sin 4\pi y_1$	0	...	0	...
0	0	$\sin \pi y_1$...	0	0	0	$\sin 2\pi y_1$...	0	0	0	$\sin 3\pi y_1$...	0	0	0	$\sin 4\pi y_1$...	0	...
...
0	0	0	...	$\sin \pi y_1$	0	0	0	...	$\sin 2\pi y_1$	0	0	0	...	$\sin 3\pi y_1$	0	0	0	...	$\sin 4\pi y_1$...
0	0	0	...	0	$A_{22}^{(0)}$	0	0	...	0	$A_{23}^{(0)}$	0	0	...	0	$A_{24}^{(0)}$	0	0	...	0	...
0	0	0	...	0	0	$A_{22}^{(1)}$	0	...	0	0	$A_{23}^{(1)}$	0	...	0	0	$A_{24}^{(1)}$	0	...	0	...
0	0	0	...	0	0	0	$A_{22}^{(2)}$...	0	0	0	$A_{23}^{(2)}$...	0	0	0	$A_{24}^{(2)}$...	0	...
...
0	0	0	...	0	0	0	0	...	$A_{22}^{(2)}$	0	0	0	...	$A_{23}^{(2)}$	0	0	0	...	$A_{24}^{(2)}$...
0	0	0	...	0	0	0	0	...	0	$A_{33}^{(0)}$	0	0	...	0	$A_{34}^{(0)}$	0	0	...	0	...
0	0	0	...	0	0	0	0	...	0	0	$A_{33}^{(1)}$	0	...	0	0	$A_{34}^{(1)}$	0	...	0	...
0	0	0	...	0	0	0	0	...	0	0	0	$A_{33}^{(2)}$...	0	0	0	$A_{34}^{(2)}$...	0	...
...
0	0	0	...	0	0	0	0	...	0	0	0	0	...	$A_{33}^{(2)}$	0	0	0	...	$A_{34}^{(2)}$...
...
0	0	0	...	0	0	0	0	...	0	$A_{43}^{(0)}$	0	0	...	0	$A_{44}^{(0)}$	0	0	...	0	...
0	0	0	...	0	0	0	0	...	0	0	$A_{43}^{(1)}$	0	...	0	0	$A_{44}^{(1)}$	0	...	0	...
0	0	0	...	0	0	0	0	...	0	0	0	$A_{43}^{(2)}$...	0	0	0	$A_{44}^{(2)}$...	0	...
...
0	0	0	...	0	0	0	0	...	0	0	0	0	...	$A_{43}^{(2)}$...	0	0	0	...	$A_{44}^{(2)}$
...

di mana $A_{33}^{(2)} = A_{33}^{(1)} - \frac{A_{32}^{(1)}}{A_{22}^{(1)}} \cdot A_{23}^{(1)}$. Secara umum: $A_{ij}^{(2)} = A_{ij}^{(1)} - \frac{A_{i2}^{(1)}}{A_{22}^{(1)}} \cdot A_{2j}^{(1)}$.

Setelah iterasi ke-(N-1), diperoleh matriks segi tiga atas dengan nilai determinan:

$$= (\sin \pi y_1)^M \cdot (A_{22}^{(1)})^M \cdot (A_{33}^{(2)})^M \cdot \dots \cdot (A_{NN}^{(N-1)})^M = \left[\prod_{i=1}^N (A_{ii}^{(i-1)}) \right]^M$$

Dengan menggunakan (4), maka terbukti bahwa

$$\text{Det } \mathbf{A}^y = \begin{vmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \dots & \sin N\pi y_1 \\ \sin \pi y_2 & \sin 2\pi y_2 & \sin 3\pi y_2 & \dots & \sin N\pi y_2 \\ \sin \pi y_3 & \sin 2\pi y_3 & \sin 3\pi y_3 & \dots & \sin N\pi y_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi y_N & \sin 2\pi y_N & \sin 3\pi y_N & \dots & \sin N\pi y_N \end{vmatrix}^M \quad \blacksquare$$

Teorema:

Jika $\mathbf{A} =$

$$\begin{bmatrix} \sin \pi x_1 \cdot \sin \pi y_1 & \dots & \sin M\pi x_1 \cdot \sin \pi y_1 & \sin \pi x_1 \cdot \sin 2\pi y_1 & \dots & \sin M\pi x_1 \cdot \sin 2\pi y_1 & \dots & \dots & \sin \pi x_1 \cdot \sin N\pi y_1 & \dots & \sin M\pi x_1 \cdot \sin N\pi y_1 \\ \vdots & & & & & & & & & & \vdots \\ \sin \pi x_M \cdot \sin \pi y_1 & \dots & \sin M\pi x_M \cdot \sin \pi y_1 & \sin \pi x_M \cdot \sin 2\pi y_1 & \dots & \sin M\pi x_M \cdot \sin 2\pi y_1 & \dots & \dots & \sin \pi x_M \cdot \sin N\pi y_1 & \dots & \sin M\pi x_M \cdot \sin N\pi y_1 \\ \sin \pi x_1 \cdot \sin \pi y_2 & \dots & \sin M\pi x_1 \cdot \sin \pi y_2 & \sin \pi x_1 \cdot \sin 2\pi y_2 & \dots & \sin M\pi x_1 \cdot \sin 2\pi y_2 & \dots & \dots & \sin \pi x_1 \cdot \sin N\pi y_2 & \dots & \sin M\pi x_1 \cdot \sin N\pi y_2 \\ \vdots & & & & & & & & & & \vdots \\ \sin \pi x_M \cdot \sin \pi y_2 & \dots & \sin M\pi x_M \cdot \sin \pi y_2 & \sin \pi x_M \cdot \sin 2\pi y_2 & \dots & & \dots & \dots & & & \vdots \\ \vdots & & & & & & & & & & \vdots \\ \vdots & & & & & & & & & & \vdots \\ \sin \pi x_M \cdot \sin \pi y_N & \dots & \sin M\pi x_M \cdot \sin \pi y_N & \sin \pi x_M \cdot \sin 2\pi y_N & \dots & & \dots & \dots & & & \vdots \\ \vdots & & & & & & & & & & \vdots \\ \sin \pi x_M \cdot \sin \pi y_N & \dots & \sin M\pi x_M \cdot \sin \pi y_N & \sin \pi x_M \cdot \sin 2\pi y_N & \dots & & \dots & \dots & & & \sin M\pi x_M \cdot \sin N\pi y_N \end{bmatrix}$$

maka: $\text{Det } \mathbf{A} \neq 0$.

Bukti:

Dari (1) diperoleh : $\det \mathbf{A} = \det \mathbf{A}^x \cdot \det \mathbf{A}^y$
Kemudian berdasarkan proposisi 1 dan 2 didapat:

$$\text{Det } \mathbf{A} = \begin{vmatrix} \sin \pi x_1 & \sin 2\pi x_1 & \sin 3\pi x_1 & \dots & \sin M\pi x_1 \\ \sin \pi x_2 & \sin 2\pi x_2 & \sin 3\pi x_2 & \dots & \sin M\pi x_2 \\ \sin \pi x_3 & \sin 2\pi x_3 & \sin 3\pi x_3 & \dots & \sin M\pi x_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi x_M & \sin 2\pi x_M & \sin 3\pi x_M & \dots & \sin M\pi x_M \end{vmatrix}^N \cdot \begin{vmatrix} \sin \pi y_1 & \sin 2\pi y_1 & \sin 3\pi y_1 & \dots & \sin N\pi y_1 \\ \sin \pi y_2 & \sin 2\pi y_2 & \sin 3\pi y_2 & \dots & \sin N\pi y_2 \\ \sin \pi y_3 & \sin 2\pi y_3 & \sin 3\pi y_3 & \dots & \sin N\pi y_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sin \pi y_N & \sin 2\pi y_N & \sin 3\pi y_N & \dots & \sin N\pi y_N \end{vmatrix}^M$$

Karena masing-masing $\det \mathbf{A}^x$, dan $\det \mathbf{A}^y \neq 0$, maka $\det \mathbf{A} \neq 0$. ■

3. Eksistensi fungsi $u(x,y)$ yang Melalui K Buah Titik Sembarang

Dalam bagian ini akan dibahas eksistensi fungsi $u(x,y)$ yang melalui K buah titik sembarang (x_i, y_i, c_i) dengan $0 < x_i < 1$, dan $0 < y_i < 1$ untuk $i = 1, 2, \dots, K$.

Pembahasan akan dibagi dalam dua kasus berbeda.

Kasus-1:

Apabila $x_i \neq x_j$ dan $y_i \neq y_j$ untuk setiap i dan j , maka pandanglah $u(x,y)$ yang melalui K^2 buah titik sehingga K buah titik di atas merupakan bagian di dalamnya. Berdasarkan masalah pada poin 2 di atas maka dijamin ada $u(x,y)$ yang melalui K^2 buah titik tadi, yang berarti juga melalui K buah titik asalnya.

Kasus-2:

Apabila $x_i = x_j$ untuk suatu i dan j , serta $y_s = y_t$ untuk suatu s dan t , maka x_i dan y_i dapat disusun ulang sedemikian sehingga $0 < x_1 < x_2 < \dots < x_M < 1$ dan $0 < y_1 < y_2 < \dots < y_N < 1$ dengan M dan N masing-masing lebih kecil dari K . Selanjutnya pandanglah $u(x,y)$ yang melalui $(M.N)$ buah titik sehingga K buah titik di atas merupakan bagian di dalamnya. Dengan demikian berdasarkan masalah pada poin 2 di atas maka dijamin ada $u(x,y)$ yang melalui $(M.N)$ buah titik tadi, yang berarti juga melalui K buah titik asalnya.

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